

**QUASILINEAR NONLOCAL INTEGRODIFFERENTIAL
EQUATIONS IN BANACH SPACES**

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ABSTRACT . In this paper , we study the existence of mild solutions for quasi -
linear integrodifferential equations with nonlocal conditions in Banach spaces .
The results are established by using Hausdorff ' s measure of noncompactness .

1 . INTRODUCTION

In this paper , we discuss the existence of mild solution of the following nonlinear
integrodifferential equation with nonlocal condition

$$\frac{du(t)}{dt} = A(t, u)u + \int_0^t f(t, s, u(s))ds, \quad t \in [0, b], \quad (1.1)$$

$$u(0) = g(u) + u_0, \quad (1.2)$$

where $f : [0, b] \times [0, b] \times \mathbb{X} \rightarrow \mathbb{X}$ and $A : [0, b] \times \mathbb{X} \rightarrow \mathbb{X}$ are continuous functions ,
 $g : \mathcal{C}([0, b]; \mathbb{X}) \rightarrow \mathbb{X}$, $u_0 \in \mathbb{X}$ and \mathbb{X} is a real Banach space with norm $\| \cdot \|$.

The notion of “ nonlocal condition ” has been introduced to extend the study of the
classical initial value problems ; see , e . g . [4 , 8 , 1 0 , 1 1 , 1 9] . It is more precise
for

describing nature phenomena than the classical condition since more information is taken
into account , thereby decreasing the negative effects incurred by a possi - bly erroneous
single measurement taken at the initial time . The study of abstract nonlocal initial
value problems was initiated by Byszewski , we refer to some of the papers below .
Byszewski [6 , 7] , Byszewski and Lasmikauthem [9] give the exis - tence and
uniqueness of mild solutions and classical solutions when f and g satisfy Lipschitz - type
conditions . Subsequently , many authors are devoted to studying of nonlocal problems .
See [1 , 2 , 1 2 , 1 3 , 1 5 , 20] for the references and remarks about the advantage
of the nonlocal problems over the classical initial value problems .

This article is motivated by the recent paper of Chandrasekaran [1 0] . We use
some hypotheses in [1 0] , and using the method of Hausdorff ' s measure of noncom -
pactness , we give the existence of mild solutions of quasilinear integrodifferential

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equations with nonlocal conditions (1 . 1) - (1 . 2) . Our results improve and extend some corresponding results in [2 , 7 , 8 , 1 0 , 1 5] .

2 . PRELIMINARIES

Throughout this paper \mathbb{X} will represent a Banach space with norm $\| \cdot \|$. Denoted $\mathcal{C}([0, b]; \mathbb{X})$ by the space of \mathbb{X} - valued continuous functions on $[0, b]$ with the norm $\| u \| = \sup \{ \| u(t) \|, t \in [0, b] \}$ for $u \in \mathcal{C}([0, b]; \mathbb{X})$, and denoted $\mathcal{L}(0, b; \mathbb{X})$ by the space of \mathbb{X} - valued Bochner integrable functions on $[0, b]$ with the norm $\| u \|_{\mathcal{L}} = \int_0^b \| u(t) \| dt$.

The Hausdorff ' s measure of noncompactness $\beta_{\mathbb{Y}}$ is defined by $\beta_{\mathbb{Y}}(B) = \inf \{ r > 0, B \text{ can be covered by finite number of balls with radii } r \}$ for bounded set B in a Banach space \mathbb{Y} .

Lemma 2 . 1 ([3]) . Let \mathbb{Y} be a real Banach space and $B, C \subseteq \mathbb{Y}$ be bounded , with the following properties :

(1) B is pre - compact if and only if $\beta_{\mathbb{X}}(B) = 0$;
 (2) $\beta_{\mathbb{Y}}(B) = \beta_{\mathbb{Y}}(\overline{B}) = \beta_{\mathbb{Y}}(\text{conv} B)$, where \overline{B} and $\text{conv} B$ mean the closure and convex hull of B respectively ;

(3) $\beta_{\mathbb{Y}}(B) \leq \beta_{\mathbb{Y}}(C)$, where $B \subseteq C$;

(4) $\beta_{\mathbb{Y}}(B + C) \leq \beta_{\mathbb{Y}}(B) + \beta_{\mathbb{Y}}(C)$, where $B + C = \{ x + y : x \in B, y \in C \}$;

(5) $\beta_{\mathbb{Y}}(B \cup C) \leq \max \{ \beta_{\mathbb{Y}}(B), \beta_{\mathbb{Y}}(C) \}$;

(6) $\beta_{\mathbb{Y}}(\lambda B) \leq |\lambda| \beta_{\mathbb{Y}}(B)$ for any $\lambda \in \mathbb{R}$;

(7) If the map $Q : D(Q) \subseteq \mathbb{Y} \rightarrow \mathbb{Z}$ is Lipschitz continuous with constant k , then $\beta_{\mathbb{Z}}(QB) \leq k\beta_{\mathbb{Y}}(B)$ for any bounded subset $B \subseteq D(Q)$, where \mathbb{Z} be a Banach space ;

(8) $\beta_{\mathbb{Y}}(B) = \inf \{ d_{\mathbb{Y}}(B, C) ; C \subseteq \mathbb{Y} \text{ is precompact } \} = \inf \{ d_{\mathbb{Y}}(B, C) ; C \subseteq \mathbb{Y} \text{ is finite valued } \}$, where $d_{\mathbb{Y}}(B, C)$ means the nonsymmetric (or symmetric) Hausdorff distance between B and C in \mathbb{Y} ;

(9) If $\{W_n\}_{n=1}^{+\infty}$ is decreasing sequence of bounded closed nonempty subsets of

\mathbb{Y} and $\lim_{n \rightarrow \infty} \beta_{\mathbb{Y}}(W_n) = 0$, then $\bigcap_{n=1}^{+\infty} W_n$ is nonempty and compact in \mathbb{Y} .

The map $Q : W \subseteq \mathbb{Y} \rightarrow \mathbb{Y}$ is said to be a $\beta_{\mathbb{Y}}$ - contraction if there exists a positive constant $k < 1$ such that $\beta_{\mathbb{Y}}(Q(B)) \leq k\beta_{\mathbb{Y}}(B)$ for any bounded closed subset $B \subseteq W$, where \mathbb{Y} is a Banach space .

Lemma 2 . 2 (Darbo - Sadovskii [3]) . If $W \subseteq \mathbb{Y}$ is bounded closed and convex , the continuous map $Q : W \rightarrow W$ is a $\beta_{\mathbb{Y}}$ - contraction , then the map Q has at least one fixed point in W .

In this paper we denote by β the Hausdorff ' s measure of noncompactness of \mathbb{X} and denote $\beta_{\mathcal{C}}$ by the Hausdorff ' s measure of noncompactness of $\mathcal{C}([a, b]; \mathbb{X})$. To discuss the existence , we need the following Lemmas in this paper .

Lemma 2 . 3 ([3]) . If $W \subseteq \mathcal{C}([0, b]; \mathbb{X})$ is bounded , then $\beta(W(t)) \leq \beta_{\mathcal{C}}(W)$ for all $t \in [0, b]$, where $W(t) = \{u(t); u \in W\} \subseteq \mathbb{X}$. Furthermore if W is equicontinuous on

$[a, b]$, then $\beta(W(t))$ is continuous on $[a, b]$ and $\beta_{\mathcal{C}}(W) = \sup \{ \beta(W(t)), t \in [a, b] \}$.

Lemma 2 . 4 ([1 4]) . If $\{u_n\}_{n=1}^{\infty} \subset \mathcal{L}^1(a, b; \mathbb{X})$ is uniformly integrable , then the function $\beta(\{u_n(t)\}_{n=1}^{\infty})$ is measurable and

$$\beta(\{ \int_0^t u_n(s) ds \}_{n=1}^{\infty}) \leq 2 \int_0^t \beta(\{u_n(s)\}_{n=1}^{\infty}) ds. \quad (2.1)$$

$$\beta\left(\int_0^t W(s)ds\right) \leq \int_0^t \beta(W(s))ds. \tag{2.2}$$

From [10], we know that for any fixed $u \in \mathcal{C}([0, b]; \mathbb{X})$ there exist a unique continuous function $U_u : [0, b] \times [0, b] \rightarrow B(\mathbb{X})$ defined on $[0, b] \times [0, b]$ such that

$$U_u(t, s) = I + \int_s^t A_u(\omega)U_u(\omega, s)d\omega, \tag{2.3}$$

where $B(\mathbb{X})$ denote the Banach space of bounded linear operators from \mathbb{X} to \mathbb{X} with the norm $\|Q\| = \sup\{\|Qu\| : \|u\| = 1\}$, and I stands for the identity operator on \mathbb{X} , $A_u(t) = A(t, u(t))$. From (2.3), we have

$$U_u(t, t) = I, \quad U_u(t, s)U_u(s, r) = U_u(t, r), \quad (t, s, r) \in [0, b] \times [0, b] \times [0, b],$$

$\frac{\partial U_u(t, s)}{\partial t} = A_u(t)U_u(t, s)$ for almost all $t \in [0, b], \forall s \in [0, b]$. **Definition 2.6.** A continuous function $u(t) \in \mathcal{C}([0, b]; \mathbb{X})$ such that

$$u(t) = U_u(t, 0)u_0 + U_u(t, 0)g(u) + \int_0^t U_u(t, s) \int_0^s f(s, \tau, u(\tau))dsd\tau \tag{2.4}$$

and $u(0) = g(u) + u_0$ is called a mild solution of (1.1) – (1.2).

The evolution family $\{U_u(t, s) | 0 \leq s \leq t \leq b\}$ is said to be equicontinuous if $(t, s) \rightarrow \{U_u(t, s)x : x \in B\}$ is equicontinuous for $t > 0$ and for all bounded subset B in \mathbb{X} . The following Lemma is obvious.

Lemma 2.7. If the evolution family $\{U_u(t, s) | 0 \leq s \leq t \leq b\}$ is equicontinuous and $\eta \in \mathcal{L}(0, b; \mathbb{R}^+)$, then the set $\{\int_0^t U_u(t-s, s)u(s)ds, \|u(s)\| \leq \eta(s) \text{ for a.e. } s \in [0, b]\}$ is

$$\text{equicontinuous for } t \in [0, b].$$

In section 3, we give some existence results when g is compact and f satisfies the conditions with respect to Hausdorff's measure of noncompactness. In section 4, we use the different method to discuss the case when g is Lipschitz continuous and f satisfies the conditions with the Hausdorff's measure of noncompactness.

In this paper, we denote $M = \sup\{\|U_u(t, s)\| : (t, s) \in [0, b] \times [0, b]\}$ for all $u \in \mathbb{X}$. Without loss of generality, we let $u_0 = 0$.

3. THE EXISTENCE RESULTS FOR COMPACT g

In this section by using the usual techniques of the Hausdorff's measure of noncompactness and its applications in differential equations in Banach spaces (see, e.g. [3, 5, 14]), we give some existence results of the nonlocal problem (1.1) – (1.2). Here we list the following hypotheses:

(HA) : The evolution family $\{U_u(t, s) | 0 \leq s \leq t \leq b\}$ generated by $A(t, u)$ is equicontinuous, and $\|U_u(t, s)\| \leq M$ for almost all $t, s \in [0, b]$.

(Hg) (1) $g : \mathcal{C}([0, b]; \mathbb{X}) \rightarrow \mathbb{X}$ is continuous and compact;

(2) There exist $N > 0$ such that $\|g(u)\| \leq N$ for all $u \in \mathcal{C}([0, b]; \mathbb{X})$.

(Hf) (1) $f : [0, b] \times [0, b] \times \mathbb{X} \rightarrow \mathbb{X}$ satisfies the *Carath é odory - type* condition ; i . e . , $f(\cdot, \cdot, u)$ is measurable for all $u \in \mathbb{X}$ and $f(t, s, \cdot)$ is continuous for

a.e. $t, s \in [a, b]$;

(2) There exist two functions $h : [0, b] \times \mathbb{R}^+ \rightarrow \mathbb{R}^+$ and $q : [0, b] \times \mathbb{R}^+ \rightarrow \mathbb{R}^+$ such that $h(\cdot, r) \in \mathcal{L}(0, b; \mathbb{R}^+)$ for every $r \geq 0$, $h(t, \cdot)$ is continuous and increasing, $q(s) \in \mathcal{L}(0, b; \mathbb{R}^+)$, and $\|f(t, s, u)\| \leq q(t)h(s, \|u\|)$ for a . e . $t \in [0, b]$, and all $u \in \mathcal{C}([0, b]; \mathbb{X})$, and for all positive constants

K_1, K_2 , the scalar equation

$$m(t) = K_1 + K_2 \int_0^t h(s, m(s)) ds, \quad t \in [0, b] \quad (3.1)$$

has at least one solution ;

(3) There exist $\eta \in \mathcal{L}(0, b; \mathbb{R}^+)$, $\zeta \in \mathcal{L}(0, b; \mathbb{R}^+)$ such that $\beta(f(t, s, D)) \leq \eta(t)\zeta(s)\beta(D)$ for a . e . $t, s \in [0, b]$, and for any bounded subset $D \subset$

$$\mathcal{C}([0, b]; \mathbb{X}). \text{ Here we let } \int_0^t \eta(s) ds \leq K$$

Now , we give an existence result under the above hypotheses .

Theorem 3 . 1 . Assume the hypotheses (HA) , (Hf) , (Hg) are satisfied , then the nonlocal initial value problem (1 . 1) - (1 . 2) has at least one mild solution .

Proof . Let $m(t)$ be a solution of the scalar equation

$$m(t) = MN + RM \int_0^t h(s, m(s)) ds, \quad (3.2)$$

where $R = \int_0^t q(s) ds$. Defined a map $Q : \mathcal{C}([0, b]; \mathbb{X}) \rightarrow \mathcal{C}([0, b]; \mathbb{X})$ by

$$(Qu)(t) = U_u(t, 0)g(u) + \int_0^t U_u(t, s) \int_0^s f(s, \tau, u(\tau)) d\tau ds, \quad t \in [0, b] \quad (3.3)$$

for all $u \in \mathcal{C}([0, b]; \mathbb{X})$. We can show that Q is continuous by the usual techniques (see , e . g . [16 , 17]) .

We denote by $W_0 = \{u \in \mathcal{C}([0, b]; \mathbb{X}), \|u(t)\| \leq m(t) \text{ for all } t \in [0, b]\}$. Then $W_0 \subseteq \mathcal{C}([0, b]; \mathbb{X})$ is bounded and convex .

Define $W_1 = \text{---}_{\text{conv}} K(W_0)$, where ---_{conv} means the closure of the convex hull in $\mathcal{C}([0, b]; \mathbb{X})$. As $U_u(t, s)$ is equicontinuous , g is compact and $W_0 \subseteq \mathcal{C}([0, b]; \mathbb{X})$ is bounded , due to Lemma 2 . 7 and hypothesis (Hf)(2), $W_1 \subseteq \mathcal{C}([0, b]; \mathbb{X})$ is bounded closed convex nonempty and equicontinuous on $[0, b]$.

For any $u \in Q(W_0)$, we know

$$\begin{aligned} \|u(t)\| &\leq MN + M \int_0^t \int_0^s q(s)h(\tau, m(\tau)) d\tau ds \\ &\leq MN + M \int_0^t h(\tau, m(\tau)) d\tau \int_0^t q(s) ds \\ &\leq MN + MR \int_0^t h(s, m(s)) ds \\ &= m(t) \end{aligned}$$

for $t \in [0, b]$. It follows that $W_1 \subset W_0$.

We define $W_{n+1} = \text{---}_{\text{conv}} Q(W_n)$, for $n = 1, 2, \dots$. Form above we know that $\{W_n\}_{n=1}^\infty$ is a decreasing sequence of bounded , closed , convex , equicontinuous on $[0, b]$ and nonempty subsets in $\mathcal{C}([0, b]; \mathbb{X})$.

Now for $n \geq 1$ and $t \in [0, b]$, $W_n(t)$ and $Q(W_n(t))$ are bounded subsets of \mathbb{X} , hence , for any $\varepsilon > 0$, there is a sequence $\{u_k\}_{k=1}^\infty \subset W_n$ such that (see , e . g . [5] , pp . 125)

$$\begin{aligned}
 & \beta(W_{n+1}(t)) = \beta(QW_n(t)) \\
 & \leq 2\beta\left(\int_0^t U_u(t,s) \int_0^s f(s,\tau, \{u_k(\tau)\}_{k=1}^\infty) d\tau ds\right) + \varepsilon \\
 & \leq 2M \int_0^t \beta\left(\int_0^s f(s,\tau, \{u_k(\tau)\}_{k=1}^\infty) d\tau\right) ds + \varepsilon \\
 & \leq 4M \int_0^t \int_0^s \beta(f(s,\tau, \{u_k(\tau)\}_{k=1}^\infty)) d\tau ds + \varepsilon \\
 & \leq 4M \int_0^t \int_0^s \eta(s)\zeta(\tau)\beta(\{u_k(\tau)\}_{k=1}^\infty) d\tau ds + \varepsilon \\
 & \leq 4M \int_0^t \zeta(\tau)\beta(W_n(\tau)) d\tau \int_0^t \eta(s) ds + \varepsilon \\
 & \leq 4MK \int_0^t \zeta(s)\beta(W_n(s)) ds + \varepsilon.
 \end{aligned}$$

Since $\varepsilon > 0$ is arbitrary, it follows from the above inequality that

$$\beta(QW_{n+1}(t)) \leq 4MK \int_0^t \zeta(s)\beta(W_n(s)) ds \tag{3.4}$$

for all $t \in [0, b]$. Because W_n is decreasing for n , we define

$$\alpha(t) = \lim_{n \rightarrow \infty} \beta(W_n(t))$$

for all $t \in [0, b]$. From (3.4), we have

$$\alpha(t) \leq 4MK \int_0^t \zeta(s)\alpha(s) ds$$

for $t \in [0, b]$, which implies that $\alpha(t) = 0$ for all $t \in [0, b]$. By Lemma 2.3, we

know that $\lim_{n \rightarrow \infty} \beta C(W_n) = 0$. Using Lemma 2.1, we know that $W = \bigcap_{n=1}^\infty W_n$

is convex compact and nonempty in $C([0, b]; \mathbb{X})$ and $Q(W) \subset W$. By the famous Schauder's fixed point theorem, there exists at least one mild solution u of the initial value problem (1.1) - (1.2), where $u \in W$ is a fixed point of the continuous

map Q . □

Remark 3.2. If the function f is compact or Lipschitz continuous (see, e.g. [6, 16, 18]), then (Hf)(3) is automatically satisfied.

In some of the early related results in references and above result, it is supposed that the map g is uniformly bounded. We indicate here that this condition can be released. In fact, if g is compact, then it must be bounded on bounded set. Here we

give an existence result under another growth condition of f (see, [11, 20]), when

g is not uniformly bounded. Precisely, we replace the hypothesis (Hf)(2) by (Hf)(2'). There exists a function $p \in \mathcal{L}(0, b; \mathbb{R}^+)$ and an increasing function $\psi : \mathbb{R}^+ \rightarrow \mathbb{R}^+$ such that $\|f(t, s, u)\| \leq p(t)\psi(\|u\|)$, for a.e. $t \in [0, b]$, and all $u \in$

$$\mathcal{C}([0, b]; \mathbb{X}).$$

6 Q. DONG, G. LI, J. ZHANG EJDE - 28 / 19 **Theorem 3.3.** Suppose that (HA), (Hf) (1), (Hf) (2'), (Hf) (3), (Hg) (1) are satisfied. Then the equation (1.1) - (1.2) has at least one mild solution if

$$\limsup_{k \rightarrow \infty} \frac{M}{k} (\varphi(k) + b\psi(k) \int_0^b p(s) ds) < 1, \quad (3.5)$$

where $\varphi(k) = \sup\{\|g(u)\|, \|u\| \leq k\}$.

Proof. The inequality (3.5) implies that there exists a constant $k > 0$ such that

$$M(\varphi(k) + b\psi(k) \int_0^b p(s) ds) < k.$$

Just as in the proof of Theorem 3.1, let $W_0 = \{u \in C([0, b]; \mathbb{X}) : \|u(t)\| \leq k\}$ and $W_1 = \text{---}_{\text{conv}} QW_0$. Then for any $u \in W_1$, we have

$$\begin{aligned} \|u(t)\| &\leq M\varphi(k) + M \int_0^t \int_0^s p(\tau) \psi(k) d\tau ds \\ &\leq M\varphi(k) + bM\psi(k) \int_0^b p(s) ds < k \end{aligned}$$

for $t \in [0, b]$. It means that $W_1 \subset W_0$. So we can complete the proof similarly to Theorem 3.1 \square

4. EXISTENCE RESULTS FOR LIPSCHITZ g

In the previous section, we obtained the existence results when g is compact but without the compactness of $\{U_u(t, s) : 0 \leq s \leq t \leq b\}$ or f . In this section, we discuss the equation (1.1) - (1.2) when g is Lipschitz and f is not Lipschitz. Precisely, we

replace (Hg) (1) by
(Hg) (1') There exist a constant $L \in (0, \frac{1}{M})$ such that $\|g(u) - g(v)\| \leq L \|u - v\|$
for

every $u, v \in C([0, b]; \mathbb{X})$.

Theorem 4.1. Let (HA), (Hg) (1') (2), (Hf) be satisfied. Then the equation (1.1) - (1.2) has at least one mild solution provided that

$$ML + 4MK \int_0^b \zeta(s) ds < 1. \quad (4.1)$$

Proof. We define $Q1, Q2 : C([0, B]; \mathbb{X}) \rightarrow C([0, B]; \mathbb{X})$ by

$$\begin{aligned} (Q1^u)(t) &= U_u(t, 0)g(u), \\ (Q2^u)(t) &= \int_0^t U_u(t, s) \int_0^s f(s, \tau, u(\tau)) d\tau ds \end{aligned}$$

for $u \in C([0, B]; \mathbb{X})$. Note that $Q1 + Q2 = Q$, as defined in the proof of Theorem 3.1. We define $W_0 = \{u \in C([0, B]; \mathbb{X}) : \|u(t)\| \leq m(t) \ \forall t \in [0, b]\}$, and let $W = \text{---}_{\text{conv}} QW_0$. Then from the proof of Theorem 3.1 we know that W is a bounded closed convex and equicontinuous subset of $C([0, B]; \mathbb{X})$ and $QW \subset W$. We shall prove that Q is $\beta\mathcal{C}$ -contraction on W . Then Darbo - Sadovskii's fixed point theorem can be used to get a fixed point of Q in W , which is a mild solution of (1.1) - (1.2). First, for every bounded subset $B \subset W$, from the (Hg) (1') and Lemma 2.1 we have

$$\beta\mathcal{C}(Q1^B) = \beta\mathcal{C}(U_B(t,0)g(B)) \leq M\beta\mathcal{C}(g(B)) \leq ML\beta\mathcal{C}(B). \quad (4.2)$$

EJDE - 2018 / 19 NONLOCAL INTEGRODIFFERENTIAL EQUATIONS 7 Next , for every bounded subset $B \subset W$, for $t \in [0, b]$ and every $\varepsilon > 0$, there is a sequence $\{u_k\}_{k=1}^\infty \subset B$, such that

$$\beta(Q2^B(t)) \leq 2\beta(\{Q2^u k(t)\}_{k=1}^\infty) + \varepsilon.$$

Note that B and $Q2^B$ are equicontinuous , we can get from Lemma 2 . 1 , Lemma 2 . 4 , Lemma 2 . 5 and (Hf) (3) that

$$\begin{aligned} \beta(Q2^B(t)) &\leq 2M \int_0^t \beta\left(\int_0^s f(s, \tau, \{u_k(\tau)\}_{k=1}^\infty) d\tau\right) ds + \varepsilon \\ &\leq 4M \int_0^t \int_0^s \beta(f(s, \tau, \{u_k(\tau)\}_{k=1}^\infty)) d\tau ds + \varepsilon \\ &\leq 4M \int_0^t \int_0^s \eta(s)\zeta(\tau)\beta(\{u_k(\tau)\}_{k=1}^\infty) d\tau ds + \varepsilon \\ &\leq 4M \int_0^t \zeta(\tau)\beta(B(\tau)) d\tau \int_0^t \eta(s) ds + \varepsilon. \\ &\leq 4MK \int_0^t \zeta(\tau)\beta(B(\tau)) d\tau + \varepsilon \\ &\leq 4MK\beta\mathcal{C}(B) \int_0^b \zeta(s) ds + \varepsilon \end{aligned}$$

Taking supremum in $t \in [0, b]$, we have

$$\beta\mathcal{C}(Q2^B) \leq 4MK\beta\mathcal{C}(B) \int_0^b \zeta(s) ds + \varepsilon.$$

Since $\varepsilon > 0$ is arbitrary , we have

$$\beta\mathcal{C}(Q2^B) \leq 4MK\beta\mathcal{C}(B) \int_0^b \zeta(s) ds \tag{4.3}$$

for any bounded $B \subset W$.

Now , for any subset $B \subset W$, due to Lemma 2 . 1 , (4 . 2) and (4 . 3) we have

$$\begin{aligned} \beta\mathcal{C}(QB) &\leq \beta\mathcal{C}(Q1^B) + \beta\mathcal{C}(Q2^B) \\ &\leq (ML + 4MK \int_0^b \zeta(s) ds)\beta\mathcal{C}(B). \end{aligned}$$

By (4 . 1) we know that Q is a $\beta\mathcal{C}$ - contraction on W . By Lemma 2 . 2 , there is a fixed point u of Q in W , which is a solution of (1 . 1) - (1 . 2) . This completes the proof . \square

Now we give an existence result without the uniform boundedness of g .

Theorem 4 . 2 . *Suppose that (HA) , (Hf) (1) , (Hf) (2 ') , (Hf) (3) , (Hg) (1 ') are satisfied . Then the equation (1 . 1) - (1 . 2) has at least one mild solution if (4 . 1) and the following condition are satisfied*

$$ML + bM \int_0^b p(s) ds \limsup_{k \rightarrow \infty} \frac{\psi(k)}{k} < 1. \tag{4.4}$$

Proof . From (4 . 4) and the fact that $L < 1$, there exists a constant $k > 0$ such that

$$M(kL + bM \int_0^b p(s) ds \psi(k) + \|g(0)\|) < k.$$

8 Q. DONG, G. LI, J. ZHANG EJDE - 28 / 19 We define $W_0 = \{u \in \mathcal{C}([0, b]); \mathbb{X} : \|u(t)\| \leq k, \forall t \in [0, b]\}$. Then for every $u \in W_0$, we have

$$\begin{aligned} \|Qu(t)\| &\leq M(\|g(u)\| + \psi(k) \int_0^t \int_0^s p(\tau) d\tau ds) \\ &\leq M(\|g(u) - g(0) + g(0)\| + b\psi(k) \int_0^t p(s) ds) \\ &\leq M(kL + \|g(0)\| + b\psi(k) \int_0^t p(\tau) d\tau) < k \end{aligned}$$

for $t \in [0, b]$. This means that $QW_0 \subset W_0$. Define $W = \text{---}_{\text{conv}} QW_0$. The above proof also implies that $QW \subset W$. So we can prove the theorem similar with Theorem 4.1. \square

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