

ON A NONLINEAR INTEGRAL EQUATION WITHOUT COMPACTNESS

F . ISAIA

ABSTRACT . The purpose of this paper is to obtain an existence result for the integral equation

$$u(t) = \varphi(t, u(t)) + \int_a^b \psi(t, s, u(s))ds, \quad t \in [a, b]$$

where $\varphi : [a, b] \times \mathbb{R} \rightarrow \mathbb{R}$ and $\psi : [a, b] \times [a, b] \times \mathbb{R} \rightarrow \mathbb{R}$ are continuous functions which satisfy some special growth conditions . The main idea is to transform the integral equation into a fixed point problem for a condensing map $T : C[a, b] \rightarrow C[a, b]$.

The “ a priori estimate method ” (which is a consequence of the invariance under homotopy of the degree defined for α - condensing perturbations of the identity) is used in order to prove the existence of fixed points for T . Note that the assumptions on functions φ and ψ do not generally assure the compactness of operator T , therefore the Leray - Schauder degree cannot be used (see K . Deimling [2 , Example 9 . 1 , p . 69]) .

1 . INTRODUCTION

The topological methods proved to be a powerful tool in the study of various problems which appear in nonlinear analysis . Particularly , the a priori estimate method (or the method of a priori bounds) has been often used in order to prove the existence of solutions for some boundary value problems for nonlinear differential equations or nonlinear partial differential equations . For example , J . Mawhin uses this method together with the coincidence degree and shows that under appropriate assumptions , the boundary value problem

$$\begin{cases} -x''(t) = f(t, x(t), x'(t)), & t \in [0, \pi] \\ x(0) = x(\pi) = 0 \end{cases}$$

and the problem

$$\begin{cases} x'(t) = f(t, x(t)), & t \in [0, 1] \\ x(0) = x(1) \end{cases}$$

admit solutions (see J . Mawhin [6 , Sections V . 2 and VI . 2]) . This method is also used (but together with the Leray - Schauder degree) in G . Dinca , P . Jebelean [3]

Received September 18 , 2005 .

2000 *Mathematics Subject Classification* . Primary 45 G 10 , 47 H 9 , 47 H 10 , 47 H 11 .

Key words and phrases . Nonlinear integral equation , condensing map , topological degree , a priori estimate method .

234 F . ISAIA and G . Dinca , P . Jebelean , J . Mawhin [4] to prove the existence of solutions for the problem

$$\begin{cases} -\Delta_p u = f(t, u) & \text{in } \Omega \\ u|_{\partial\Omega} = 0. \end{cases}$$

In the present paper , the a priori estimate method is used together with the degree for condensing maps in order to prove the existence of solutions for the integral equation

$$u(t) = \varphi(t, u(t)) + \int_a^b \psi(t, s, u(s)) ds, \quad t \in [a, b], \quad (1)$$

under appropriate assumptions on functions φ and ψ . The result presented herein is in relation with a result of F . Isaia [5] . The hypothesis imposed on functions φ and ψ are stronger (and considerably simpler) , but the result is stronger as well , namely the solution u of equation (1) is in $C[a, b]$, while in F . Isaia [5] , we obtained

$$u \in L^p(a, b).$$

2 . THE TOPOLOGICAL DEGREE FOR CONDENSING MAPS For a minute description of the following notions we refer the reader to K . Deimling

[2].

In the following , X will be a Banach space and $\mathcal{B} \subset \mathcal{P}(X)$ will be the family of all its bounded sets .

Definition 1 . The function $\alpha : \mathcal{B} \rightarrow \mathbb{R}_+$ defined by $\alpha(B) = \inf \{d > 0 : B \text{ admits a finite cover by sets of diameter } \leq d\}$, $B \in \mathcal{B}$, is called the (Kuratowski -) measure of noncompactness .

In the whole paper , the letter α will only be used in this context . We state without proof some properties of this measure .

Proposition 1 . The following assertions hold :

- (a) $\alpha(B) = 0$ iff B is relatively compact .
- (b) α is a seminorm , i . e .

$$\alpha(\lambda B) = |\lambda| \alpha(B) \quad \text{and} \quad \alpha(B_1 + B_2) \leq \alpha(B_1) + \alpha(B_2).$$

$$(c) \quad B_1 \subset B_2 \text{ implies } \alpha(B_1) \leq \alpha(B_2);$$

$$\alpha(B_1 \cup B_2) = \max\{\alpha(B_1), \alpha(B_2)\}.$$

$$(d) \quad \alpha(\text{conv} B) = \alpha(B).$$

$$(e) \quad \alpha(\overline{B}) = \alpha(B).$$

Definition 2 . Consider $\Omega \subset X$ and $F : \Omega \rightarrow X$ a continuous bounded map . We say that F is α - Lipschitz if there exists $k \geq 0$ such that

$$\alpha(F(B)) \leq k\alpha(B) \quad (\forall) B \subset \Omega \text{ bounded.}$$

ON A NONLINEAR INTEGRAL EQUATION WITHOUT COMPACTNESS 235 If , in addition , $k < 1$, then we say that F is a strict α - contraction . We say that F is α - condensing if

$$\alpha(F(B)) < \alpha(B) \quad (\forall) B \subset \Omega \text{ bounded with } \alpha(B) > 0.$$

In other words , $\alpha(F(B)) \geq \alpha(B)$ implies $\alpha(B) = 0$. The class of all strict α - contractions $F : \Omega \rightarrow X$ is denoted by $SC_\alpha(\Omega)$ and the class of all α - condensing maps $F : \Omega \rightarrow X$ is denoted by $C_\alpha(\Omega)$.

We remark that $SC_\alpha(\Omega) \subset C_\alpha(\Omega)$ and every $F \in C_\alpha(\Omega)$ is α - Lipschitz with constant $k = 1$. We also recall that $F : \Omega \rightarrow X$ is Lipschitz if there exists $k > 0$ such that

$$\|Fx - Fy\| \leq k \|x - y\| \quad (\forall) x, y \in \Omega$$

and that F is a strict contraction if $k < 1$.

Next , we state without proof some properties of the applications defined above .

Proposition 2 . *If $F, G : \Omega \rightarrow X$ are α - Lipschitz maps with constants k, k' , then $F + G : \Omega \rightarrow X$ is α - Lipschitz with constant $k + k'$.*

Proposition 3 . *If $F : \Omega \rightarrow X$ is compact , then F is α - Lipschitz with constant*

$$k = 0.$$

Proposition 4 . *If $F : \Omega \rightarrow X$ is Lipschitz with constant k , then F is α - Lipschitz with the same constant k .*

The theorem below asserts the existence and the basic properties of the topological degree for α - condensing perturbations of the identity .

Let

$$\mathcal{T} = \left\{ \begin{array}{l} (I - F, \Omega, y) : \quad \Omega \subset X \text{ open and bounded,} \\ F \in C_\alpha(\text{---}\Omega), \quad y \in X \setminus (I - F)(\partial\Omega) \end{array} \right\}$$

be the family of the admissible triplets . There exists one degree function $D : \mathcal{T} \rightarrow \mathbb{Z}$ which satisfies the properties :

Theorem 1 . (D 1) $D(I, \Omega, y) = 1$ for every $y \in \Omega$ (Normalization) .
 (D 2) For every disjoint , open sets $\Omega_1, \Omega_2 \subset \Omega$ and every $y \in \Omega \setminus (I - F)(\partial(\Omega_1 \cup \Omega_2))$ we have

$$D(I - F, \Omega, y) = D(I - F, \Omega_1, y) + D(I - F, \Omega_2, y)$$

(Additivity on domain) . (D 3) $D(I - H(t, \cdot), \Omega, y(t))$ is independent of $t \in [0, 1]$ for every continuous , bounded map $H : [0, 1] \times \Omega \rightarrow X$ which satisfies

$$\alpha(H([0, 1] \times B)) < \alpha(B) \quad (\forall) B \subset \Omega \text{ with } \alpha(B) > 0$$

and every continuous function $y : [0, 1] \rightarrow X$ which satisfies

$$y(t) \neq x - H(t, x) \quad (\forall) t \in [0, 1], (\forall) x \in \partial\Omega$$

(*Invariance under homotopy*) . (D 4) $D(I-F, \Omega, y) \neq 0$ implies $y \in (I-F)(\Omega)$ (*Existence*) .

(D 5) $D(I - F, \Omega, y) = D(I - F, \Omega_1, y)$ for every open set $\Omega_1 \subset \Omega$ and every

$$y \in \Omega \setminus \Omega_1 \quad (\text{Excision}).$$

Having in hand a degree function defined on \mathcal{T} , we study the usability of the “a priori estimate method” by means of this degree.

Theorem 2. *Let $F : X \rightarrow X$ be α -condensing and*

$$S = \{x \in X : (\exists)\lambda \in [0, 1] \text{ such that } x = \lambda Fx\}.$$

If S is a bounded set in X , so there exists $r > 0$ such that $S \subset B_r(0)$, then

$$D(I - \lambda F, B_r(0), 0) = 1 \quad (\forall)\lambda \in [0, 1].$$

Consequently, F has at least one fixed point and the set of the fixed points of F lies in $B_r(0)$.

Proof. First, we remark that every affine homotopy of α -condensing maps is an admissible homotopy. To see this, let us consider a bounded open set $\Omega \subset X$, the maps $F_1, F_2 \in C_\alpha(\overline{\Omega})$ and let $H : [0, 1] \times \Omega \rightarrow X$ be defined by

$$H(t, x) = (1 - t)F_1x + tF_2x.$$

For every $B \subset \Omega$ with $\alpha(B) > 0$ we have

$$H([0, 1] \times B) \subset \text{conv}(F_1(B) \cup F_2(B))$$

and, using Proposition 1,

$$\begin{aligned} \alpha(H([0, 1] \times B)) &\leq \alpha(\text{conv}(F_1(B) \cup F_2(B))) \\ &= \alpha(F_1(B) \cup F_2(B)) \\ &= \max\{\alpha(F_1(B)), \alpha(F_2(B))\} < \alpha(B). \end{aligned}$$

Next, we fix $\lambda \in [0, 1]$ and we consider the affine homotopy between the α -

$$\text{condensing maps } \lambda F, 0 \in C_\alpha(X)$$

$$H : [0, 1] \times X \rightarrow X, \quad H(t, x) = (1 - t)0x + t\lambda Fx = t\lambda Fx.$$

By the previous argument,

$$\alpha(H([0, 1] \times B)) < \alpha(B) \quad (\forall) B \subset X \text{ bounded with } \alpha(B) > 0.$$

If $x \in X$ and $t \in [0, 1]$ verify $x - H(t, x) = 0$, then $x \in S \subset B_r(0)$. Thus, we can use the properties (D 3), (D 1) of the degree and we obtain

$$\begin{aligned} D(I - \lambda F, B_r(0), 0) &= D(I - H(1, \cdot), B_r(0), 0) \\ &= D(I - H(0, \cdot), B_r(0), 0) \\ &= D(I, B_r(0), 0) = 1. \end{aligned}$$

Finally, the property (D 4) of the degree is used. \square

$$u(t) = \varphi(t, u(t)) + \int_a^b \psi(t, s, u(s))ds, \quad t \in [a, b],$$

where $\varphi : [a, b] \times \mathbb{R} \rightarrow \mathbb{R}$ and $\psi : [a, b] \times [a, b] \times \mathbb{R} \rightarrow \mathbb{R}$ are continuous functions which satisfy the following conditions :

(a) There exist $C_1, M_1 \geq 0$, $q_1 \in [0, 1)$ such that

$$| \varphi(t, x) | \leq C_1 | x |^{q_1} + M_1$$

forevery $(t, x) \in [a, b] \times \mathbb{R}$.

(b) There exists $K_1 \in [0, 1)$ such that

$$| \varphi(t, x) - \varphi(t, y) | \leq K_1 | x - y |$$

forevery $(t, x), (t, y) \in [a, b] \times \mathbb{R}$.

(c) There exist $C_2, M_2 \geq 0$, $q_2 \in [0, 1)$ such that

$$| \psi(t, s, x) | \leq C_2 | x |^{q_2} + M_2$$

forevery $(t, s, x) \in [a, b] \times [a, b] \times \mathbb{R}$.

Under these assumptions , we will show that equation (1) has at least one solu -

tion $u \in C[a, b]$.

Define operators

$$F : C[a, b] \rightarrow C[a, b], \quad (Fu)(t) = \varphi(t, u(t)), \quad t \in [a, b],$$

$$G : C[a, b] \rightarrow C[a, b], \quad (Gu)(t) = \int_a^b \psi(t, s, u(s))ds, \quad t \in [a, b],$$

$$T : C[a, b] \rightarrow C[a, b], \quad Tu = Fu + Gu.$$

Then , equation (1) can be written as

$$u = Tu. \tag{2}$$

Thus , the existence of a solution for equation (1) is equivalent to the existence of a fixed point for operator T .

Proposition 5 . *The operator $F : C[a, b] \rightarrow C[a, b]$ is Lipschitz with constant*

K_1 . *Consequently F is α - Lipschitz with the same constant K_1 .*

Proof . From (b) , we have

$$\begin{aligned} \| Fu - Fv \|_{C[a, b]} &= \sup_{t \in [a, b]} | (Fu)(t) - (Fv)(t) | \\ &= \sup_{t \in [a, b]} | \varphi(t, u(t)) - \varphi(t, v(t)) | \\ &\leq K_1 \sup_{t \in [a, b]} | u(t) - v(t) | = K_1 \| u - v \|_{C[a, b]}, \end{aligned}$$

for every $u, v \in C[a, b]$. By Proposition 4, F is α -Lipschitz with constant K_1 .

Moreover, F satisfies the following growth condition :

$$\|Fu\|_{C[a,b]} \leq C_1 \|u\|_{C[a,b]}^{q_1} + M_1, \quad (3)$$

for every $u \in C[a, b]$. Relation (3) is a simple consequence of condition (a). \square

Proposition 6. *The operator $G : C[a, b] \rightarrow C[a, b]$ is compact. Consequently G is α -Lipschitz with zero constant.*

Proof. First, we prove the continuity of G . Let $(u_n) \subset C[a, b]$, $u \in C[a, b]$ be such that $\|u_n - u\|_{C[a,b]} \rightarrow 0$. We have to show that $\|Gu_n - Gu\|_{C[a,b]} \rightarrow 0$. Fix $\varepsilon > 0$. There exists a constant $K \geq 0$ such that

$$\begin{aligned} \|u_n\|_{C[a,b]} &\leq K \quad (\forall) n \in \mathbb{N}^*, \\ \|u\|_{C[a,b]} &\leq K. \end{aligned}$$

Using the uniform continuity of ψ on $[a, b] \times [a, b] \times [-K, K]$, we derive that there exists $\delta = \delta(\varepsilon) > 0$ such that

$$|\psi(t_1, s_1, x_1) - \psi(t_2, s_2, x_2)| \leq \frac{\varepsilon}{b-a},$$

for every $(t_1, s_1, x_1), (t_2, s_2, x_2) \in [a, b] \times [a, b] \times [-K, K]$ such that $|t_1 - t_2| + |s_1 - s_2| + |x_1 - x_2| < \delta$. From $\|u_n - u\|_{C[a,b]} \rightarrow 0$, it follows that there exists

$$\begin{aligned} N = N(\varepsilon) \in \mathbb{N}^* \text{ such that} \\ \sup_{t \in [a,b]} |u_n(t) - u(t)| < \delta, \end{aligned}$$

for every $n \geq N$. Consequently,

$$\begin{aligned} \|Gu_n - Gu\|_{C[a,b]} &= \sup_{t \in [a,b]} \left| \int_a^b \psi(t, s, u_n(s)) ds - \int_a^b \psi(t, s, u(s)) ds \right| \\ &\leq \sup_{t \in [a,b]} \int_a^b |\psi(t, s, u_n(s)) - \psi(t, s, u(s))| ds < \varepsilon, \end{aligned}$$

for every $n \geq N$. The continuity of G is proved.

Moreover, G satisfies the following growth condition :

$$\|Gu\|_{C[a,b]} \leq C_2(b-a) \|u\|_{C[a,b]}^{q_2} + (b-a)M_2, \quad (4)$$

for every $u \in C[a, b]$. Relation (4) is a simple consequence of condition (c).

In order to prove the compactness of G , we consider a bounded set $M \subset C[a, b]$ and we will show that $G(M)$ is relatively compact in $C[a, b]$ with the help of Arzela-Ascoli theorem. Let $-K \geq 0$ be such that

$$\|u\|_{C[a,b]} \leq K,$$

for every $u \in M$. By (4), we have

$$\|Gu\|_{C[a,b]} \leq (b-a)[C_2 K^{q_2} + M_2],$$

for every $u \in M$, so $G(M)$ is bounded in $C[a, b]$. Fix $\varepsilon > 0$. Using the uniform continuity of ψ on $[a, b] \times [a, b] \times [\text{---}K, \text{---}K]$, we derive that there exists $\delta = \delta(\varepsilon) > 0$ such that

$$|\psi(t_1, s_1, x_1) - \psi(t_2, s_2, x_2)| \leq \frac{\varepsilon}{b-a},$$

for every $(t_1, s_1, x_1), (t_2, s_2, x_2) \in [a, b] \times [a, b] \times [\text{---}K, \text{---}K]$ such that $|t_1 - t_2| + |s_1 - s_2| + |x_1 - x_2| < \delta$. If $t_1, t_2 \in [a, b]$ satisfy $|t_1 - t_2| < \delta$, then

$$|(Gu)(t_1) - (Gu)(t_2)| \leq \int_a^b |\psi(t_1, s, u(s)) - \psi(t_2, s, u(s))| ds < \varepsilon,$$

for every $u \in M$. The set $G(M) \subset C[a, b]$ satisfies the hypothesis of Arzela - Ascoli theorem, so $G(M)$ is relatively compact in $C[a, b]$.

By Proposition 3, G is α -Lipschitz with zero constant. \square

Now, we have the possibility to prove the main result of this paper.

Theorem 3. *If the functions $\varphi : [a, b] \times \mathbb{R} \rightarrow \mathbb{R}$ and $\psi : [a, b] \times [a, b] \times \mathbb{R} \rightarrow \mathbb{R}$ satisfy the conditions (a), (b), (c), then the integral equation*

$$u(t) = \varphi(t, u(t)) + \int_a^b \psi(t, s, u(s)) ds, \quad t \in [a, b],$$

has at least one solution $u \in C[a, b]$ and the set of the solutions of equation (1) is

$$\text{bounded in } C[a, b].$$

Proof. Let $F, G, T : C[a, b] \rightarrow C[a, b]$ be the operators defined in the beginning of this section. They are continuous and bounded. Moreover, F is α -Lipschitz with constant $K_1 \in [0, 1]$ and G is α -Lipschitz with zero constant (see Propositions 5 and 6). Proposition 2 shows us that T is a strict α -contraction with constant K_1 . Set

$$S = \{u \in C[a, b] : (\exists) \lambda \in [0, 1] \text{ such that } u = \lambda Tu\}.$$

Next, we prove that S is bounded in $C[a, b]$. Consider $u \in S$ and $\lambda \in [0, 1]$ such that $u = \lambda Tu$. It follows from (3) and (4) that

$$\begin{aligned} \|u\|_{C[a, b]} &= \lambda \|Tu\|_{C[a, b]} \leq \lambda (\|Fu\|_{C[a, b]} + \|Gu\|_{C[a, b]}) \\ &\leq \lambda [C_1 \|u\|_{C[a, b]}^{q_1} + C_2(b-a) \|u\|_{C[a, b]}^{q_2} + M_1 + (b-a)M_2]. \end{aligned}$$

This inequality, together with $q_1 < 1$, $q_2 < 1$, shows us that S is bounded in

$$C[a, b].$$

Consequently, by Theorem 2 we deduce that T has at least one fixed point and the set of the fixed points of T is bounded in $C[a, b]$. \square

Remark 1.

(i) if the growth condition (a) is formulated for $q_1 = 1$, then the conclusions of Theorem 3 remain valid provided that $C_1 < 1$;

(ii) if the growth condition (c) is formulated for $q_2 = 1$, then the conclusions of

Theorem 3 remain valid provided that $(b - a)C_2 < 1$;

(i ii) if the growth conditions (a) and (c) are formulated for $q_1 = 1$ and $q_2 = 1$,

then the conclusions of Theorem 3 remain valid provided that

$$C_1 + (b - a)C_2 < 1.$$

Remark 2 . The conclusions of Theorem 3 remain valid provided that equation (1) is replaced by

$$u(t) = \varphi(t, u(t)) + \int_a^t \psi(t, s, u(s))ds, \quad t \in [a, b].$$

Only slight modifications in the proof of Proposition 6 are needed .

REFERENCES

- 1 . Brezis H . , *Analyse fonctionnelle . Théorie et applications* , Masson , 1 987 .
 - 2 . Deimling K . , *Nonlinear functional analysis* , Springer - Verlag , 1 985 .
 - 3 . Dinca G . and Jebelean P . , *Une méthode de point fixe pour le p - Laplacien* , C . R . Acad . Sci . Paris , **324** (I) (1 997) , 1 65 – 1 68 .
 - 4 . Dinca G . , Jebelean P . and Mawhin J . , *Variational and topological methods for Dirichlet problems with p - Laplacian* , Portugaliae Mathematica , 58 (3) (2001) , 339 – 378 .
 - 5 . Isaia F . , *An existence result for a nonlinear integral equation without compactness* , PanAmerican Mathematical Journal , 14 (4) (2004) , 93 – 106 .
 - 6 . Mawhin J . , *Topological degree methods in nonlinear boundary value problems* , CMBS Regional Conference Series in Mathematics , **40** , American Mathematical Society , Providence , R . I . , 1 979 .
- F . Isaia , “ Transilvania ” University of Brasov , Faculty of Mathematics and Computer Science , Department of Equations , Iuliu Maniu 50 , 50009 1 Brasov , Romania ,
e - mail : i sai af lor in @y^{a-h}oo . com